Verification Experiments on the Lower Back Burden caused by Posture and Environment during Lifting Operations

Tomoka Kimura

Graduate School of Engineering, University of Miyazaki, 1-1, Gakuen Kibanadai-Nishi, Miyazaki, 889-2192, Japan

Yutaro Fujino

Faculty of Engineering, University of Miyazaki, 1-1, Gakuen Kibanadai-Nishi, Miyazaki, 889-2192, Japan

Sachiko Kido

Interdisciplinary Graduate School of Agriculture and Engineering, University of Miyazaki, 1-1, Gakuen Kibanadai-Nishi, Miyazaki, 889-2192, Japan

Praveen Nuwantha Gunaratne

Interdisciplinary Graduate School of Agriculture and Engineering, University of Miyazaki, 1-1, Gakuen Kibanadai-Nishi, Miyazaki, 889-2192, Japan

Hiroki Tamura

Faculty of Engineering, University of Miyazaki, 1-1, Gakuen Kibanadai-Nishi, Miyazaki, 889-2192, Japan

E-mail: hi19014@student.miyazaki-u.ac.jp, hi20035@student.miyazaki-u.ac.jp, z321t01@student.miyazaki-u.ac.jp, ti20060@student.miyazaki-u.ac.jp, htamura@cc.miyazaki-u.ac.jp

Abstract

One of the measures to prevent back pain is the use of appropriate posture corrections. In generally, the Squat method (method of keeping the knees bent and the waist as straight as possible) is recommended over the Stoop method (method of keeping the knees straight and the waist bent). The results of previous studies using acceleration and muscle potentials have shown that the lifting with knees in a kneeling position reduces the amount of load born by the lower back. However, few studies discuss the case where there is an obstacle between the subject and the object to be lifted and further, the scenarios where the object is away from the body's center of gravity. Therefore, this research focus on analyzing three types of movements using the AnyBody musculoskeletal mechanics analysis software, the Yo-bukun back pain prevention application, and the Delsys surface EMG and verifying the amount of lower back burden when there is an obstacle between the lifting object and the subject. This paper presents the verification results.

Keywords: Lower back burden, Posture correction, EMG, The body's center of gravity

1. Introduction

Frequent lifting activities in the construction and nursing care industries place a heavy burden on the lower back and can easily lead to lower back pain. One of the measures that can be taken by individuals to prevent back pain is to improve posture. There are two main types of lifting movements: the Stoop method (keeping the knees straight and the hips flexed) and the Squat method (keeping the knees flexed and the hips as straight as

possible). The Japanese Ministry of Health, Labour and Welfare's "Guidelines for Prevention of Back Pain in the Workplace" recommends the knee-bend lifting method. The results of the previous study and the analysis using the "Yo-bukun" application for measuring back strain showed that the lifting method with the knees bent reduced the amount of back strain compared to the lifting method without knees bent [1], [2], [3]. In addition, the previous study showed that the lifting method with the knees bent was associated with a lower EMG burden

when the lifting object was located close to the body's center of gravity [4], [5].

However, few previous studies have discussed the case where there is an obstacle between the lifting object and the subject and also when the object is far from the body's center of gravity. Therefore, the purpose of this paper is to analyze three types of movements using the AnyBody musculoskeletal mechanics analysis software, Yo-bukun back pain prevention application, and the Delsys surface electromyograph, in order to verify the amount of back burden when there is an obstacle between the lifting object and the subject.

2. Methodology

In this paper, lumbar burden was measured using AnyBody, Yo-bukun applications, and Delsys EMG.

2.1. Measuring equipments

AnyBody is a musculoskeletal mechanics analysis software from Terrabyte Co. Basically, it calculates the forces acting on each part of the human body, such as muscle activity, muscle force, and joint moments, when a movement is applied to a musculoskeletal model using inverse dynamics analysis.

Yo-bukun is an application developed by the University of Miyazaki in collaboration with DENSAN Corporation for the prevention of back pain for the iPhone. It is calibrated when the user stands upright, and calculates the amount of lumbar burden based on the tilt of the iPhone.

Delsys is the generic name for Trigno EMG system incorporated with some additional sensors developed by Delsys. In addition to EMG, IMU sensors (accelerometer, gyroscope, and magnetometer) are built in to collect kinematic data (angles) at the same time.

2.2. Measurement method

A video camera footage was used as the method of measurement for the analysis by AnyBody application. Under Yo-bukun approach, subjects were asked to keep their iPhones installed with Yo-bukun application, in their chest pockets for the measurement. EMG based approach employs two EMG sensors placed on the subject's erector spinae. The positioning of the lumbar EMG sensors is shown in the Fig. 1. The left side sensor is considered as the first channel and the right side sensor is the second channel.

The subjects were all healthy adult males, 174 ± 3 cm tall and 22 ± 1 years old. Subject identifiers are A, B, and C respectively. The movement to be measured was the lifting and lowering of an object while kneeling on one knee. The dimensions of the object (a box), are $35(W) \times 23.5(D) \times 31(H)$ cm and the weight is 1 kg. Three types of movements were measured to examine the effects of

the presence of an obstacle and the distance between the centers of gravity. The size of the obstacle was $51(W)\times10(D)\times51(H)$ cm. The subject's center of gravity was set at the pelvis. The experimental apparatus is shown in the Fig. 2.

The initial measurement was a subject lifting the object as close as possible to its body's center of gravity without placing any obstacles. The step wise process involves a subject lifting the object and remaining for 5 seconds, before lowering it. The distance between the center of gravity of the object and the subject's center of gravity was 10 cm. In the second measurement, the obstacle is in place, and the subject lowers the object to behind the obstacle starting from an apparatus configuration as in Fig. 2, subsequently returns it to the top of the obstacle. Upon lowering the object behind the obstacle, the subject stood upright and maintained the position for a duration of 5 seconds.



Fig.1. EMG sensor placements



Fig.2 . Experimental apparatus (includes the lifting object and the obstacle)



Fig.3 Posture in which the center of gravity of both the subject and the object 10 cm



Fig.4 . Posture in which the center of gravity of both the subject and the object 30 cm

Then, the subject knelt down once more and raised the object back over the obstacle. The distance between the object's center of gravity and the subject's center of gravity was 30 cm. The third measurement closely resembled the second, with the distance between the center of gravity of the object and that of the subject being 45 cm. The postures observed during such measurements at the distance between the center of gravity of the object and that of the subject being 10 cm and 30 cm are depicted in Fig 3 and Fig. 4.

After that the transition of the amount of burden applied on the lower back during such movements were calculated using AnyBody and Yo-bukun. Later, the analysis incorporates the maximum and average values of the amount of burden observed here. The Delsys measured the EMG potentials of the lower back during movements. To reduce the influence of noise, the rate of increase was calculated by dividing the difference between the mean value of the EMG during movement and the mean value of the EMG at rest by the mean value of the EMG at rest. The resting EMG potentials refer to

the potentials recorded when the subject is at rest for a 5-second interval between lifting and lowering movements.

3. Results

This chapter outlines the measurement outcomes for the three equipment types and provides a comparison between them. The movements are individually analyzed for lifting and lowering at center-of-gravity distances of 10 cm, 30 cm, and 45 cm, respectively.

3.1. Similarity between AnyBody and Yo-bukun

To validate the reliability of Yo-bukun, the similarity between AnyBody and Yo-bukun was assessed. Verification utilized the measurement data of subject B, analyzable with A. The coefficients of determination for each center-of-gravity distance are presented in Table 1. A somewhat stronger correlation was evident in the data at a center-of-gravity distance of 10 cm, while robust correlations were observed at center-of-gravity distances of 30 cm and 45 cm.

Table 1. Correlation between AnyBody and Yo-bukun (Subject B)

Center of gravity distance	\mathbb{R}^2	
(cm)		
10	0.5582	
30	0.9289	
45	0.9812	

Table 2. The rates of increase in Yo-bukun measurements

Subject	Center of	Raising	Lowering
Identity	gravity	movement	movement
	distance	(Up)	(Down)
	(cm)	%	%
	10	97.39	107.02
A	30	110.71	104.21
	45	120.70	105.34
	10	90.68	108.78
В	30	140.64	132.38
	45	172.14	163.56
	10	137.98	157.31
C	30	197.84	193.90
	45	196.63	162.03

3.2. Analysis results using Yo-bukun

The rate of increase was also determined for the Yobukun in comparison with myoelectric potentials. The rate of increase in the Yo-bukun measurements for the three movements is shown in Table 2. The comparisons for the raising and lowering movements are shown in Fig. 5 and 6, respectively. The average rate of increase was obtained by excluding the rate of increase at 10 cm. The average rate of increase was 156.44% for the lifting motion and 143.57% for the lowering motion.

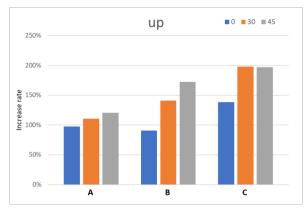


Fig.5. Yo-bukun Increase rate (up)

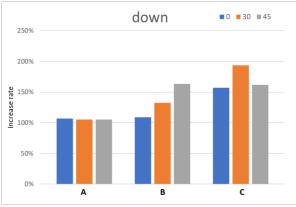


Fig.6. Yo-bukun Increase rate (down)

3.3. Analysis results using Delsys device

The rates of increase in lumbar EMG potentials during the three movements are shown in Table 3, and comparisons for raising (up) and lowering (down) movements are shown in Fig. 7 and Fig. 8, respectively. In all cases, the rate of increase was lowest when the center of gravity distance was 10 cm for each subject. For Subjects A and C, the rate of increase was higher when the center of gravity was 45 cm than when the center of gravity was 30 cm, for both lifting and lowering. For subject B, the rate of increase was higher when the center of gravity was 30 cm than when the center of gravity was 45 cm. The average rate of increase was obtained by excluding the rate of increase at 10 cm. The average rate of increase was 404.43% for the lifting motion and 394.71% for the lowering motion. The average increase was 2.59 and 2.75 times that of Yo-bukun for each operation.

Table 2. The rates of increase in lumbar EMG potentials

Subject	Center of	Raising	Lowering
Identity	gravity	movement	movement
	distance	(Up)	(Down)
	(cm)	%	%
	10	30.43	5.73
A	30	230.24	239.78
	45	339.78	296.69
	10	59.08	68.08
В	30	352.31	357.99
	45	247.76	284.30
	10	16.20	16.48
С	30	518.76	534.77
	45	737.72	654.72

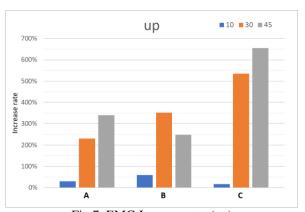


Fig.7. EMG Increase rate (up)

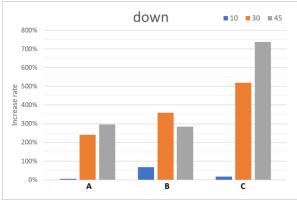


Fig.8. EMG Increase rate (down)





Fig.9 . Posture (Left: Subject B, Right: Subject C)

4. Conclusion

The rate of increase of EMG potentials during the movement was different in Subject B than in the other subjects. The possible reason for this is the difference in posture. The most notable difference is the curvature of the back. A comparison of the posture of Subject B and Subject C at a center of gravity distance of 45 cm is shown in the Fig. 9. The yellow circle at the pelvis position is the center of gravity. The white line is a simplified representation of the back. It can be seen that subject B has a straighter back than subject C. This indicates that subject B has a straighter back than subject C. This suggests that Subject B had less muscle stretch than Subject C, and that the rate of increase in myopotential was less pronounced in Subject B than in the other subjects.

In this paper, we analyzed movements using three types of measurement devices and verified the amount of lumbar burden in a situation where there is an obstacle between the subject and the lifting object. The analysis results shows that the change in the amount of lumbar burden due to the difference in the center of gravity distances was more pronounced in the electromyograms than in the measurements from the posture-based devices, such as the Anybody and the Yo-bukun. Therefore, it is possible that even in the one-kneeling lifting method, a significant distance between the object and the operator's center of gravity might not result in a reduction of electromyographic back burden.

References

- H. Tamura, K. Sakurai, K. Tanno, and Y. Fuse, "A Study on the Lumbar Burden Evaluation of Work using One Smartphone," *Journal of Robotics, Networking and Artificial Life*, vol. 5, no. 3, pp. 173–173, Jan. 2018, doi: https://doi.org/10.2991/jrnal.2018.5.3.7.
- H. Tamura, K. Sakurai, K. Tanno, and Y. Fuse, "A Study on the Lumbar Burden Evaluation of Work using One Smartphone," *Proceedings of International Conference on Artificial Life and Robotics*, vol. 23, pp. 550–553, Feb. 2018, doi: https://doi.org/10.5954/icarob.2018.os14-1.

- M. F. Antwi-Afari, H. Li, D. J. Edwards, E. A. Pärn, J. Seo, and A. Y. L. Wong, "Biomechanical analysis of risk factors for work-related musculoskeletal disorders during repetitive lifting task in construction workers," *Automation in Construction*, vol. 83, pp. 41–47, Nov. 2017, doi: https://doi.org/10.1016/j.autcon.2017.07.007.
- I. Kingma et al., "Lumbar loading during lifting: a comparative study of three measurement techniques," *Journal of Electromyography and Kinesiology*, vol. 11, no. 5, pp. 337–345, Oct. 2001, doi: https://doi.org/10.1016/s1050-6411(01)00011-6.
- C. Larivière, A. Bertrand. Arsenault, D. Gravel, D. Gagnon, and P. Loisel, "Surface electromyography assessment of back muscle intrinsic properties," *Journal of Electromyography and Kinesiology*, vol. 13, no. 4, pp. 305–318, Aug. 2003, doi: https://doi.org/10.1016/s1050-6411(03)00039-7.

Authors Introduction

Ms. Tomoka Kimura



She received her Bachelor's degree in Engineering in 2023 from the Faculty of Engineering, Miyazaki University in Japan. She is currently a master student in Miyazaki University, Japan.

Mr. Yutaro Fujino



Yutaro Fujino Born in 2001. He is currently studying in the department of environment robotics, and will receive the B,Eng from University of Miyazaki in 2024. His current reseasrch is Analysis of Low Back Burden Utilizing a Smartphone Application Called Yobukun.

Ms. Sachiko Kido



She received her M.S. from Nakamura Gakuen University, Graduate School of Human Development in 2015. Currently enrolled in the doctoral program at the Graduate School of Agriculture and Engineering, University of Miyazaki. Assistant Professor, Department of Early

Childhood Education, Higashikyushu Junior College, 2010. Lecturer, Faculty of Education, Miyazaki International University, since 2019. Her main research interest is the development of motor skills in young children.

Mr. Praveen Nuwantha Gunaratne



He received his Bachelor's degree in Engineering in 2018 from the Faculty of Engineering, University of Moratuwa, Sri Lanka. He is currently a Doctoral student in University of Miyazaki, Japan.

Prof. Hiroki Tamura



He received the B.E. and M.E. degree from Miyazaki University in 1998 and 2000, respectively. From 2000 to 2001, he was an Engineer in Asahi Kasei Corporation, Japan. In 2001, he joined Toyama University, Toyama, Japan, where he was a Technical Official in the

Department of Intellectual Information Systems. In 2006, he joined Miyazaki University, Miyazaki, Japan, where he was an Assistant Professor in the Department of Electrical and Electronic Engineering. Since 2015, he is currently a Professor in the Department of Environmental Robotics. His main research interests are Neural Networks and Optimization Problems. In recent years, he has had interest in Biomedical Signal Processing using Soft Computing.