

# Mouse Cursor Control System Using Facial Movements

Masayoshi Tabuse<sup>1</sup>, Manase Mizobe<sup>2</sup>, Yasunari Yoshitomi<sup>1</sup>, Taro Asada<sup>1</sup>

*1 Graduate School of Life and Environmental Sciences, Kyoto Prefectural University,  
1-5 Nakaragi-cho, Shimogamo, Sakyo-ku, Kyoto 606-8522, Japan*

*E-mail: tabuse@kpu.ac.jp*

*2 TORAY ENGINEERING Co.,Ltd*

*3-22 Yaesu Ryumeikan Building, Yaesu 1-chome, Chuo-ku, Tokyo 103-0028, Japan*

## Abstract

It is necessary to support of computer operation for a physically disabled person. One of the possible physical movements of the physically disabled person is facial movement. Recognition of facial movement of a person makes it possible to operate a computer. Furthermore without the adjustment for a user and adjustment for the distance from a user, it is possible to reduce the burden on a user. We developed a system to resolve these problems. In our system, a web camera, dlib C++ library and OpenCV library are used to extract feature points of the face and obtain the face direction. Changing the face direction, we can move a mouse cursor. Recognizing an open mouth or closed eye, we can carry out an operation of mouse click. In this paper, we evaluated the effect on operability due to the face direction and recognition rate due to distance.

*Keywords:* Mouse cursor system, dlib C++ library, facial movements, Physically disabled people.

## 1. Introduction

Physically disabled people cannot move their limbs freely. It is difficult for a physically disabled person to use a computer. The importance of the computer with the information society increases as a current social background. Therefore, support of the computer operation is required. The interface for them has been developed so that they can use a computer recently. There are two types of the interface. One is the contact-type which operates while attaching the device to a body. Another is the noncontact-type which operates by recognizing the movement of a body. Although the contact-type has the advantage of easy detection of body movement, the user must attach it directly during use. On the other hand, noncontact-type must adjust parameters for a user. To resolve these problems reduce a burden for the user.

One of the possible physical movements of a physically disabled person is facial movement. This means the face direction and open and closed mouth or eyes. If a computer is operated with recognizing the facial movement, the physically disabled person can use

it. We developed a system which operates a computer by the facial movement. In the previous study[1], we proposed a mouse cursor control system using Kinect. However Kinect got out of production. Therefore we developed a mouse cursor control system using a web camera instead of Kinect. Our system consists of a computer, a web camera, dlib C++ library[2] and OpenCV library[3]. It extracts feature points of the face and estimates the face direction. We can move a mouse cursor by changing the face direction. We can carry out an operation of mouse click by recognizing an open mouth or closed eye. This reduces the burden on the user.

## 2. Proposed System

### 2.1. System overview

In our system, a computer, a web camera, dlib C++ library and OpenCV library are used to extract feature points of the face and estimate the face direction. Dlib is an open source C++ library containing image processing and machine learning algorithms. Dlib can extract a face

area in image and detect 68 facial feature points from the face area. OpenCV estimates a face direction using obtained facial feature points. Our system has three functions for a physically disabled person. Firstly, it can control a mouse cursor along face direction. Secondly, it can perform a mouse click by recognizing an open mouth. Finally, it can carry out a mouse click by judging the open or closed eyes. In the following subsections, these functions are explained in detail.

### 2.2. Control of a mouse cursor by face direction

Dlib extracts a face area in image and detect 68 facial feature points from the face area. We use 2 dimensional locations of 6 facial feature points (nose tip, chin, left eye left corner, right eye right corner, left mouth corner and right mouth corner). The solvePnP function in OpenCV estimates the rotation vector (the axis of rotation and the angle of rotation) of the face using these 6 locations, 3 dimensional face model and intrinsic camera parameters. The Rodrigues function in OpenCV converts the rotation vector to a rotation matrix. *pitch* and *yaw* which express a value of the angle for vertical and horizontal face directions are calculated as follows:

$$\begin{aligned} pitch &= \tan^{-1}(R_{32} / R_{33}) \\ yaw &= \tan^{-1}(R_{21} / R_{11}) \end{aligned}$$

where  $R = (R_{ij})$  is a rotation matrix.

We define the face direction vector  $\mathbf{a}$  as

$$\mathbf{a} = (yaw, pitch).$$

The control of a mouse cursor is operated according to the face direction vector  $\mathbf{a}$ . The mouse cursor is moved in the same direction as the vector. The moving speed of a mouse cursor is changed according to the size of the vector. When  $|\mathbf{a}| < 10$ , we define the face is facing to the front and the mouse cursor does not move. When  $10 \leq |\mathbf{a}| < 15$ , the mouse cursor moves slowly. When  $15 \leq |\mathbf{a}| < 20$ , the mouse cursor moves normally. When  $20 \leq |\mathbf{a}|$ , the mouse cursor moves fast.

### 2.3. Recognition of open mouth

We extract four feature points of mouth (top, bottom, left and right) using dlib, as shown in Fig. 1. The vertical length of the mouth is found by feature point coordinates of the top and bottom. The horizontal length of the mouth is found by feature point coordinates of the left and right. The rate of the open mouth  $R_m$  is expressed as  $R_m = h_m / w_m$  where  $h_m$  and  $w_m$  denote the

vertical and horizontal length of the mouth. Let  $Th_m$  be the threshold for judgment of opened or closed mouth. When  $R_m > Th_m$ , it is recognized that the mouth is opened. In the present study, the value of  $Th_m$  is set to 0.45, which was determined experimentally.

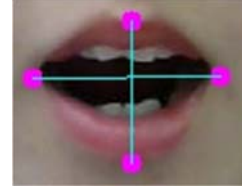


Fig. 1. Feature points of mouth extracted using dlib and the vertical and horizontal length.

### 2.4. Judgment of opened and closed eyes

We extract four feature points of eyes (top, bottom, left and right) using dlib, as shown in Fig. 2. The range of x-axis is the difference of x-coordinate between the left and right, and the range of y-axis is the difference of y-coordinate between the top and bottom. We define these ranges as eye region.

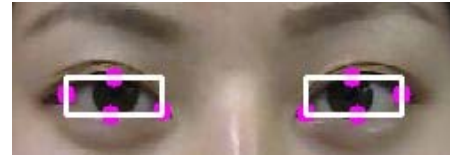


Fig. 2. Feature points of eye extracted using dlib.

The judgment of opened or closed eye uses binary images. For the binarization, at first, the detection of the eye region is performed in a RGB image. It is converted from the RGB image to a grayscale image. Then we binarize the grayscale image using discriminant analysis method[4]. The vertical and horizontal lengths of the eye are settled from the binary image, as shown in Fig. 3. We make the histogram of black pixels. The vertical length of the eye is the maximum on the histogram, and the horizontal length of the eye is the range of x-coordinate in the eye region. The rate of the open eye  $R_e$  is given by  $R_e = h_e / w_e$  where  $h_e$  and  $w_e$  denote the vertical and horizontal length of the eye. Let  $Th_e$  be the threshold for judgment of opened or closed eye. When  $R_e > Th_e$ , the eye is judged to be opening state. When  $R_e \leq Th_e$ , the eye is judged to be closing state. In the present study, the value of  $Th_e$  is set to 0.3, which was determined experimentally.

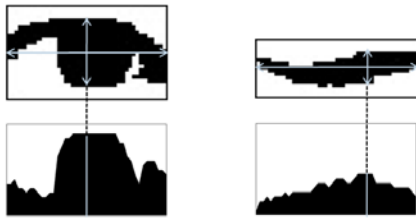


Fig. 3. The vertical and horizontal length and histogram of opened eye (left) and closed eye (right).

### 2.5. Mouse click processing

Mouse click processing is performed by recognizing the intentional movement of the user’s mouth and eyes. The movement is the following conditions:

- When the duration time of opening mouth state reach for  $t1$ ,
- When the duration time of closing eye state reach for  $t2$ ,

where  $t1$  and  $t2$  are arbitrary times. In the present study, the value of  $t1$  and  $t2$  are set to 1.0 s and 0.8 s, respectively. Mouse click processing is carried out only in the case of  $|a| < 10$ .

## 3. Experiments

### 3.1. Conditions

The experiment was performed in the following computational environment: the PC was a HP ENVY 700-560jp (CPU: Intel(R) Core(TM) i7-4790 CPU 3.60GHz, memory: 8.00GB); the OS was Microsoft Windows 8.1 Pro; the development language was Microsoft Visual C++ 2015 Express Edition and the libraries were dlib 19.16 and OpenCV 3.4.1. The image was produced by Logicool C270 HD Webcam which was placed on the top of the display, as shown in Fig. 4.



Fig. 4. Position of PC and a web camera in experiments.

### 3.2. Method

We conducted three kinds of experiments which were performed by six subjects in their twenties (2 males without glasses, 2 females without glasses and 2 females with glasses). For the first experiment, we measured times that a mouse cursor moved by face direction from a circle drawn on screen to another circle drawn in a distance of 20 cm. The subject sat at a distance of 0.8m from a web camera and moved the mouse cursor to eight directions (vertical, horizontal, and diagonal), respectively. This experiment was conducted to assess the operability by the difference of directions. For the second experiment, we examined the recognition rate of mouse click by open mouth. The distance between the web camera and the subjects was conducted at 0.6m, 0.8m, 1.0m, 1.5m, and 2.0m for evaluating influence to the recognition rate by the difference in distances. The subjects performed three times of the action of opening the mouth for one second or more. The recognition rate is the actual mouse click rate. For the last experiment, we conducted experiment to judge opened or closed eyes. This experiment was conducted at distance of 0.6m, 0.8m, 1.0m, 1.5m, and 2.0m between the web camera and subjects for evaluating influence to the judgment accuracy by the difference in distance. We evaluate the accuracy of judgment with F-measure. F-measure is expressed the following equation:

$$F = \frac{2PR}{P + R},$$

where  $P$ ,  $R$  and  $F$  denote the rate of frames which is really closing eye among frames judged as closed state, the rate of frames judged as closing state among frames which is closing eye, and the harmonic mean of precision rate  $P$  and recall rate  $R$ . We performed judgment of closed eye by visual observation.

### 3.3. Results and discussion

#### 4.3.1. Movement of mouse cursor by face direction

Fig. 5 shows the time to move the mouse cursor from a circle to another circle with 6 subjects. From the moving times of 6 subjects, it was the movement of top and bottom directions to take longer time than other directions. The subjects B and C wearing glasses took

more time to move in all directions other than the bottom left compared to subjects without glasses. It is probably because the subject's glasses frame was misrecognized as subject's eye and this misrecognition interrupt subject's operation.

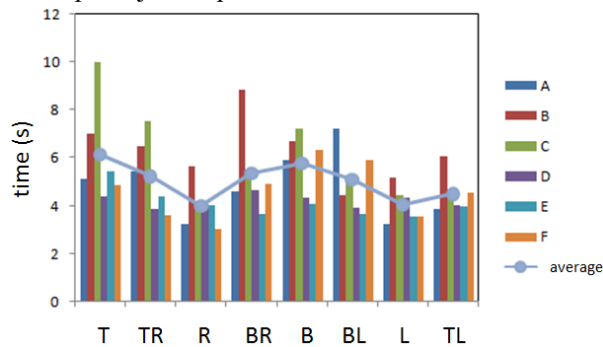


Fig. 5. Six subject A - F and Average moving time by face direction. T, TR, R, BR, B, BL, L and TL denote top, top right, right, bottom right, bottom, bottom left, left and top left directions, respectively.

#### 4.3.2. Mouse click recognition by open mouth

In the previous study[1], there was a difference in the recognition rate of mouse clicks by opening the mouth depending on the distance, but in this study, mouse clicks could be recognized at any distance. The improved recognition rate is the difference in the angle of view between Kinect and the web camera and the brightness of the image. Since the angle of view of the web camera is smaller than that of Kinect, a face in the image can be obtained larger than that of Kinect and the accuracy of feature point detection is improved. In addition, the fact that the web camera was able to obtain in a brighter image compared to Kinect led to improved feature point detection accuracy.

#### 4.3.3. Judgment accuracy of opened and closed eyes

Fig.6 shows the recognition rates of opened and closed eyes. Since the recognition rates exceeded 0.9 at all distances, it can be concluded that the judgment of opened and closed eyes was successful. This result is better than the previous study[1]. Since the angle of view of the web camera is smaller than that of Kinect, a face in the image can be obtained larger than that of Kinect and the accuracy of feature point detection is improved. In addition, the web camera was able to obtain in a brighter image compared to Kinect led and it improved feature point detection accuracy and reduced misrecognition of binarized eye areas.

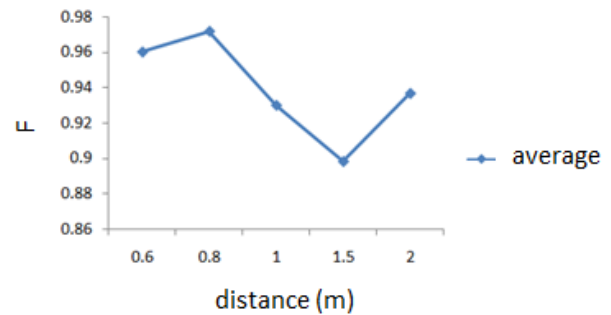


Fig. 6. F-measure of opening and closing eyes judgment.

## 4. Conclusion

We developed a mouse cursor control system for physically disabled people using a web camera, dlib and OpenCV. In this system, the user can move a mouse cursor by face direction and perform a mouse click processing by opening the user's mouth or closing the user's eye. As the results, the mouse cursor movements took more time to move up and down compared to right and left. Moreover it is somewhat difficult for a user with glasses to operate mouse cursor compared to a user without glasses. The mouse click operation performed by opening the mouth and closing the eyes did not differ in operability depending on the distance.

The future work is to improve the mouse cursor operability of a user with glasses and add other functions. Our system has only two functions, mouse cursor movement by face direction and mouse click by opening mouth and closing eyes. In order to improve practicality, it is necessary to enhance functions such as character input, double-clicking, and right-clicking.

## References

1. J. Miyachi, M. Tabuse, "Development of Mouse System for Physically Disabled Person by Face Movement Using Kinect", Proceedings of the 2017 International Conference on Artificial Life and Robotics, (2017), 124-127.
2. Dlib C++ Library, <http://dlib.net/>
3. OpenCV, <https://opencv.org/>
4. Nobuyuki Otsu, "An Automatic Threshold Selection Method Based on Discriminant and Least Squares Criteria", *The IEICE Transactions*, J63-D (1980), 349-356.