## ICAROB2024 DOIs List

ID	DOI	URL	Title
PS1	10.5954/ICAROB.2024.PS1	https://www.doi.org/10.5954/ICAROB.2024.PS1	Developing a High-Speed Working Motion of the Multi Robot in DENSO
PS2	10.5954/ICAROB.2024.PS2	https://www.doi.org/10.5954/ICAROB.2024.PS2	Experimenting with Variable Arm Quadrotors: Realizing Dynamic Configurations for
P 32	10.3934/1CAROD.2024.P32	https://www.uoi.org/10.5954/ICAROB.2024.PS2	Enhanced Flight Performance
PS3	10.5954/ICAROB.2024.PS3	https://www.doi.org/10.5954/ICAROB.2024.PS3	Artificial Intelligence and Technologies of Arm-type and Mobile Robots in Industry
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OS1-1 OS1-2	10.5954/ICAROB.2024.OS1-1 10.5954/ICAROB.2024.OS1-2	https://www.doi.org/10.5954/ICAROB.2024.0S1-1 https://www.doi.org/10.5954/ICAROB.2024.0S1-2	The Detecting Abnormal Operations in ICS Using Finite-State Machines
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OS1-3	10.5954/ICAROB.2024.0S1-4	https://www.doi.org/10.5954/ICAROB.2024.0S1-4	MiniDAM: A Dam Cybersecurity Toolkit
			A Case Study of Network-Based Intrusion Detection System Deployment in
OS1-5	10.5954/ICAROB.2024.OS1-5	https://www.doi.org/10.5954/ICAROB.2024.OS1-5	Industrial Control Systems with Network Isolation
OS1-6	10.5954/ICAROB.2024.OS1-6	https://www.doi.org/10.5954/ICAROB.2024.OS1-6	The AI integration service innovation model of real estate industry in Taiwan
OS2-1	10.5954/ICAROB.2024.OS2-1	https://www.doi.org/10.5954/ICAROB.2024.OS2-1	A Study on Sales Patterns for Vegetable Products in Retail Stores
OS2-2	10.5954/ICAROB.2024.OS2-2	https://www.doi.org/10.5954/ICAROB.2024.OS2-2	Research and Implementation of Cooperative Control for ROS Mobile Robot
OS2-3	10.5954/ICAROB.2024.OS2-3	https://www.doi.org/10.5954/ICAROB.2024.OS2-3	An OpenCV-based Method for Workpiece Residue Image Processing
OS2-4	10.5954/ICAROB.2024.OS2-4	https://www.doi.org/10.5954/ICAROB.2024.OS2-4	On Nonblockingness Verification and Enforcement of Controlled Nondeterministic
			DiscreteEvent Systems Medeling and Reachability Varification of Controlled Nondatorministic Einite State
OS2-5	10.5954/ICAROB.2024.OS2-5	https://www.doi.org/10.5954/ICAROB.2024.OS2-5	Modeling and Reachability Verification of Controlled Nondeterministic Finite-State Automata
OS3-1	10.5954/ICAROB.2024.OS3-1	https://www.doi.org/10.5954/ICAROB.2024.0S3-1	Detection and Identification of Daylily Maturity Based on YOLOv8
	40 5054 / 04 505 0004 000 0		Chaos Synchronization and Circuit Design of Chen System and L $\bar{\tau}$ $\hat{\gamma}$ System with
OS3-2	10.5954/ICAROB.2024.OS3-2	https://www.doi.org/10.5954/ICAROB.2024.0S3-2	Different Structures
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OS3-4	10.5954/ICAROB.2024.OS3-4	https://www.doi.org/10.5954/ICAROB.2024.OS3-4	A Design of Intelligent Handling Robot Based on AT89C52
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			"Green Fruit" - Intelligent Traceable Agricultural Product Production and Marketing
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OS5-6	10.5954/ICAROB.2024.OS5-6	https://www.doi.org/10.5954/ICAROB.2024.OS5-6	Construction of Anthropomorphic Grippers with Adaptive Control
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000-0	10.3334/10/00.2024.030-3		Smart Assistive Trolley for Elderly Care and Independence Parallel Cross Window Attention Transformer and CNN Model for Segmentation of
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			Endersted Learning on Brain Diacons Bassarah, Cogmonitation of Corobral Small
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OS20-3	10.5954/ICAROB.2024.0S20-4	https://www.doi.org/10.5954/ICAROB.2024.0520-5	Design of flexible mechanism for flexible manipulator
OS20-5	10.5954/ICAROB.2024.OS20-5	https://www.doi.org/10.5954/ICAROB.2024.OS20-5	Research on Driver Drowsiness Detection Method based on Deep Learning
OS20-6	10.5954/ICAROB.2024.OS20-6	https://www.doi.org/10.5954/ICAROB.2024.OS20-6	An Analysis of Translational Motion for a Mobile Robot with Line-Symmetric Rollers
0320-0	10.5354/1CAROD.2024.0320-0	11(1)S.//WWW.d01.01g/10.3334/1CANOD.2024.0320-0	Arrangement
OS20-7	10.5954/ICAROB.2024.OS20-7	https://www.doi.org/10.5954/ICAROB.2024.OS20-7	Development of Teaching Materials for Robot Programming for Junior High School
			Students: Student-Based Educational Activities
OS20-8	10.5954/ICAROB.2024.OS20-8	https://www.doi.org/10.5954/ICAROB.2024.OS20-8	Design and Software Production of Robotics Educational Design for Elementary and Junior High School Student
			Development of visual inspection system for low-reflective material utilizing of a
OS20-9	10.5954/ICAROB.2024.OS20-9	https://www.doi.org/10.5954/ICAROB.2024.0S20-9	string shadow
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			to Facilitate Crop Growth Data Analysis
OS20-11	10.5954/ICAROB.2024.OS20-11	https://www.doi.org/10.5954/ICAROB.2024.OS20-11	Development greenhouse environment prediction system using IoT data
OS20-12	10.5954/ICAROB.2024.OS20-12	https://www.doi.org/10.5954/ICAROB.2024.OS20-12	The Development of SaaS for Quantifying the Amount of Drifted Debris on the Coast
0.620 12	10 F0F4/ICADOD 2024 0020 12	https://www.doi.org/10.5954/ICAROB.2024.OS20-13	Development of antagonistic wire-driven joint mechanism capable of rapid motion
OS20-13	10.5954/ICAROB.2024.OS20-13	https://www.doi.org/10.5954/ICAROB.2024.0520-15	and variable stiffness
OS20-14	10.5954/ICAROB.2024.OS20-14	https://www.doi.org/10.5954/ICAROB.2024.OS20-14	Gakken Hills Interdisciplinary Ekiden Competing with Humans, Animals, and Robots
OS20-15	10.5954/ICAROB.2024.OS20-15	https://www.doi.org/10.5954/ICAROB.2024.OS20-15	Development of a Low-Cost Underwater Robot for Research and Education
OS21-1	10.5954/ICAROB.2024.OS21-1	https://www.doi.org/10.5954/ICAROB.2024.OS21-1	Enhancing Reconnaissance Missions Through Multiple Unmanned Systems in ROS
OS21-2	10.5954/ICAROB.2024.OS21-2	https://www.doi.org/10.5954/ICAROB.2024.OS21-2	Illumination Effects on Facial Expression Recognition using Empirical Mode
	10.0001/10/11002.2021.0021		Decomposition
OS21-3	10.5954/ICAROB.2024.OS21-3	https://www.doi.org/10.5954/ICAROB.2024.OS21-3	Supercontinuum Generation Pump By a Molybdenum Disulfide Based Soliton Mode-
			Locked Fiber Laser Adsorption Behavior of Arsenic and Selenium using NiZn Hydroxy Double Salts with
OS22-1	10.5954/ICAROB.2024.OS22-1	https://www.doi.org/10.5954/ICAROB.2024.0S22-1	Acetate, Chloride, Nitrate and Sulfate Anions
0S22-2	10.5954/ICAROB.2024.OS22-2	https://www.doi.org/10.5954/ICAROB.2024.OS22-2	Parallel acoustic analysis based on the domain decomposition method with higher-
0322-2	10.5354/16ANOB.2024.0322-2	1111ps.//www.uoi.org/10.5554/1CANOB.2024.0322-2	order element
OS22-3	10.5954/ICAROB.2024.OS22-3	https://www.doi.org/10.5954/ICAROB.2024.OS22-3	Sound field evaluation on the acoustical experiment using non-steady state analysis
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0S22-4 0S22-5	10.5954/ICAROB.2024.0S22-4 10.5954/ICAROB.2024.0S22-5	https://www.doi.org/10.5954/ICAROB.2024.OS22-4 https://www.doi.org/10.5954/ICAROB.2024.OS22-5	A Deep Insight method with Morphological Analysis Support for Museum Exhibition of Small Fungi using AR Technology
			Automatic Selection of High-Grade Dried Shiitake Mushrooms using Machine
OS22-6	10.5954/ICAROB.2024.OS22-6	https://www.doi.org/10.5954/ICAROB.2024.0S22-6	Learning
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OS23-1	10.5954/ICAROB.2024.OS23-1	https://www.doi.org/10.5954/ICAROB.2024.OS23-1	Structures: A Review on Preserving Historical Edifices Through Advanced Civil Engineering Techniques.
OS23-2	10.5954/ICAROB.2024.OS23-2	https://www.doi.org/10.5954/ICAROB.2024.OS23-2	Drones and Data: A Comprehensive Exploration of UAVs in Data Mining
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OS23-5	10.5954/ICAROB.2024.OS23-5	https://www.doi.org/10.5954/ICAROB.2024.OS23-5	Object Detection and Instance Segmentation with YOLOV8: Progress and
			Limitations
OS24-1	10.5954/ICAROB.2024.OS24-1	https://www.doi.org/10.5954/ICAROB.2024.OS24-1	A high-performance motion planning method based on asymptotically optimal RRT
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OS24-3	10.5954/ICAROB.2024.OS24-3	https://www.doi.org/10.5954/ICAROB.2024.OS24-3	Small Sample Object Detection Based on Improved YOLOv5

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OS24-5	10.5954/ICAROB.2024.OS24-5	https://www.doi.org/10.5954/ICAROB.2024.OS24-5	Optimization Analysis of a Deep Learning-Based Model for Predicting Temperature Fields in the Solidification Process of Castings
OS25-1	10.5954/ICAROB.2024.OS25-1	https://www.doi.org/10.5954/ICAROB.2024.OS25-1	Portable Green Energy Mobile Laptop Charging Station
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0S25-5	10.5954/ICAROB.2024.0S25-5	https://www.doi.org/10.5954/ICAROB.2024.0525-5	Smart Car Jack Using Internet of Things
OS25-6	10.5954/ICAROB.2024.OS25-6	https://www.doi.org/10.5954/ICAROB.2024.OS25-6	Gas Detection for Biogas System Using Internet-of-Things(IoT)
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			Classification
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			Application to Haptic Feedback for Myoelectric Prosthetic Hands
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u33-3			signal-to-noise ratio lonogram video images
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			Based System
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			Navigating Malaysia's Digital Transformation
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