

Change Detection Experimentation for Time Series data by New Sequential Probability Ratio

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Abstract

Previously, we have proposed a novel method using New Sequential Probability Ratio (NSPR) for the structural change detection problem of ongoing time series data instead of using SPRT (Sequential Probability Ratio Test). In this paper, for comparison, we present the experimental results by applying the both methods, i.e., NSPR and SPRT, to time series data that are generated by a multiple regression model in the case where one explanatory variation is a periodic function (sine function). And also we discuss the effectiveness of the both methods.

Keywords: Time series data, structural change detection, SPRT, New Sequential Probability Ratio (NSPR)

1. Introduction

Change point detection (CPD) problem in time series (see Refs.1-7) is to identify whether the generation structure of monitoring data has changed at some time point by some reason, or not. We consider that the problem is very important and that it can be applied to a wide range of application fields.

For the structural change detection problem of ongoing time series data, we have already proposed some kinds of methods (see Refs. 6, 8-12). In this paper, we present the results of comparison experiment by two methods that are Sequential Probability Ratio Test

(SPRT) and New Sequential Probability Ratio (NSPR) (Refs. 6, 11-12).

2. SPRT and Chow Test

2.1. SPRT

The Sequential Probability Ratio Test (SPRT) is used for testing a null hypothesis H_0 (e.g. the quality is under pre-specified limit 1%) against hypothesis H_1 (e.g. the quality is over pre-specified limit 1%). And it is defined as follows:

Let Z_1, Z_2, \dots, Z_i be respectively observed time series data at each stage of successive events, the probability ratio λ_i is computed as follows.

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$$\lambda_i = \frac{P(Z_1 | H_1) \cdot P(Z_2 | H_1) \cdots P(Z_i | H_1)}{P(Z_1 | H_0) \cdot P(Z_2 | H_0) \cdots P(Z_i | H_0)} \quad (1)$$

where $P(Z | H_0)$ denotes the distribution of Z if H_0 is true, and similarly, $P(Z | H_1)$ denotes the distribution of Z if H_1 is true.

Two positive constants C_1 and C_2 ($C_1 < C_2$) are chosen. If $C_1 < \lambda_i < C_2$, the experiment is continued by taking an additional observation. If $C_2 < \lambda_i$, the process is terminated with the rejection of H_0 (acceptance of H_1). If $\lambda_i < C_1$, then terminate this process with the acceptance of H_0 .

$$C_1 = \frac{\beta}{1-\alpha}, \quad C_2 = \frac{1-\beta}{\alpha} \quad (2)$$

where α means type I error (reject a true null hypothesis), and β means type II error (accept a null hypothesis as true one when it is actually false).

2.2 Procedure of SPRT

The concrete procedure of applying the SPRT method to the structural change detection problem is described.

[Step 1] Make a prediction expression and set the tolerance band (a) (e.g. $a=2\sigma_s$) that means permissible error margin between the predicted data and the observed one. (σ_s denotes a standard deviation in learning sample data at early stage.)

[Step 2] Set up the null hypothesis H_0 and alternative hypothesis H_1 .

H_0 : Change has not occurred yet.

H_1 : Change has occurred.

Set the values α , β and compute C_1 and C_2 , according to Eq. (2). Initialize $i = 0$, $\lambda_0 = 1$.

[Step 3] Incrementing i ($i = i+1$), observe the following data y_i . Evaluate the error $|\varepsilon_i|$ between the data y_i and the predicted value from the aforementioned prediction expression.

[Step 4] Judge as to whether the data y_i goes in the tolerance band or not, i.e., the ε_i is less than (or equal to) the permissible error margin or not. If it is Yes, then set $\lambda_i = 1$ and return to Step3. Otherwise, advance to Step5.

[Step 5] Calculate the probability ratio λ_i , using the below Eq.(3) that is equivalent to Eq.(1).

$$\lambda_i = \lambda_{i-1} \frac{P(\varepsilon_i | H_1)}{P(\varepsilon_i | H_0)} \quad (3)$$

where, if the data y_i goes “OUT” from the tolerance band, $(P(\varepsilon_i | H_0), P(\varepsilon_i | H_1)) = (\theta_0, \theta_1)$, otherwise (i.e., the data y_i goes “IN”), $(P(\varepsilon_i | H_0), P(\varepsilon_i | H_1)) = ((1-\theta_0), (1-\theta_1))$.

[Step 6] Execution of testing.

(i) If the ratio λ_i is greater than C_2 ($= (1-\beta)/\alpha$), dismiss the null hypothesis H_0 , and adopt the alternative hypothesis H_1 , and then End.

(ii) Otherwise, if the ratio λ_i is less than C_1 ($= \beta/(1-\alpha)$), adopt the null hypothesis H_0 , and dismiss the alternative hypothesis H_1 , and then set $\lambda_i = 1$ and return to Step3.

(iii) Otherwise (in the case where $C_1 \leq \lambda_i \leq C_2$), advance to Step7.

[Step 7] Observe the following data y_i incrementing i . Evaluate the error $|\varepsilon_i|$ and judge whether the data y_i goes in the tolerance band, or not. Then, return to Step5 (λ_i calculation).

2.3 Chow Test

The well-known Chow Test checks if there are significant differences or not, among residuals for three Regression Lines, where regression Line 1 obtained from the data before a change point t_c , Line 2 from the data after t_c , and Line 3 from the whole data so far, by setting up the change point hypothesis at each point in the whole data (Fig.1).

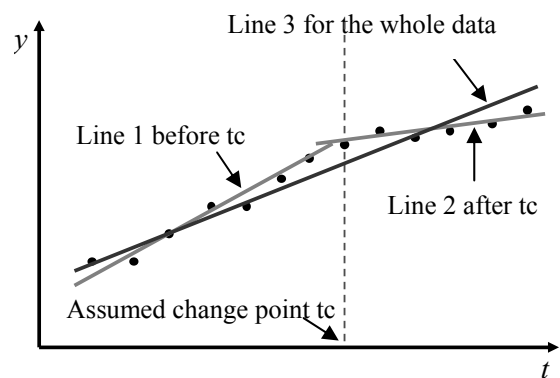


Fig.1. Conceptual image of Chow Test

3. New Sequential Probability Ratio (NSPR)

3.1. Definition of NSPR¹¹⁻¹²

Let $C_n = a_1 a_2, \dots, a_i, \dots, a_n$ $a_i \in \{\text{IN}, \text{OUT}\}$ be a string (or symbol sequence) obtained from the observed data.

Let θ_i and $\tilde{\theta}_i$ be the conditional probability that receives the observed data a_i in the state S_0 and S_1 , respectively, where S_0 and S_1 mean the state of unchanged state and changed state, respectively.

That is, it means that $\theta_i \in \{R, 1-R\}$ and $\tilde{\theta}_i \in \{R_c, 1-R_c\}$, respectively, where $R = P(\text{OUT} | S_0)$, $R_c = P(\text{OUT} | S_1)$. And let $P(C_n, H_0)$ and $P(C_n, H_1)$ be the joint probability of the symbol sequence C_n that happen with the event H_0 (the structural change is not occurred) and H_1 (the change is occurred), respectively. Then, the following equations hold.

$$P(a_1 \dots a_n, H_0) = (1-\gamma)^n \theta_1 \dots \theta_n = (1-\gamma)^n \prod_{i=1}^n \theta_i \quad (4)$$

$$\begin{aligned} P(a_1 \dots a_n, H_1) &= \gamma \prod_{i=1}^n \tilde{\theta}_i + ((1-\gamma)\theta_1)(\gamma \prod_{i=2}^n \tilde{\theta}_i) \\ &\quad + ((1-\gamma)^2 \theta_1 \theta_2)(\gamma \prod_{i=3}^n \tilde{\theta}_i) + \dots \\ &= \sum_{k=1}^n ((1-\gamma)^{k-1} \cdot \prod_{j=0}^{k-1} \theta_j)(\gamma \prod_{i=k}^n \tilde{\theta}_i) \end{aligned} \quad (5)$$

$$P(H_0 | a_1 \dots a_n) \equiv P(H_0 | C_n) = \frac{P(C_n, H_0)}{P(C_n)} \quad (6)$$

$$P(H_1 | a_1 \dots a_n) \equiv P(H_1 | C_n) = \frac{P(C_n, H_1)}{P(C_n)} \quad (7)$$

Using these above equations (Eq.(4)-(7)), the New Sequential Probability Ratio (NSPR) that we propose can be represented as follows.

$$\begin{aligned} \text{NSPR} &\equiv \frac{P(H_1 | a_1 \dots a_n)}{P(H_0 | a_1 \dots a_n)} = \frac{P(H_1 | C_n)}{P(H_0 | C_n)} = \frac{P(C_n, H_1)}{P(C_n, H_0)} \\ &= \frac{\sum_{k=1}^n ((1-\gamma)^{k-1} \cdot \prod_{j=0}^{k-1} \theta_j)(\gamma \prod_{i=k}^n \tilde{\theta}_i)}{(1-\gamma)^n \prod_{i=1}^n \theta_i} \end{aligned} \quad (8)$$

3.2. Recursive Form

When the NSPR is greater than 1.0, we can regard that the structural change has been occurred before the present time.

In the similar way as SPRT (see Eq.(3)), the definition of NSPR can also be described in a recursion formula. Let Λ_n be the value of NSPR defined by Eq.(8), we have the following recursive equation.

$$\Lambda_n = \frac{1}{1-\gamma} (\Lambda_{n-1} + \gamma) \left(\frac{\tilde{\theta}_n}{\theta_n} \right) \quad (9)$$

where $\Lambda_0 = 0$, $\theta_0 = 1$, $\tilde{\theta}_0 = 1$.

4. Experimentation for Comparison

We have done the comparison experimentation by SPRT and NSPR for a time series data that is generated based on the following equations.

$$\begin{cases} y = x_1 + 20x_2 + 5 + \varepsilon & (t \leq t_c) \\ y = x_1 + 10x_2 + 5 + \varepsilon & (t_c \leq t) \end{cases} \quad (10)$$

where $\varepsilon \sim N(0, \sigma^2)$, i.e., the error ε is subject to the Normal Distribution with the average 0 and the variation σ^2 , and t_c means the change point. In addition, we have set $t_c=70$ and $\sigma=5$. The number of the time points is 100 (i.e. .

Setting the two kinds (or cases) of coefficients in Eq.(10) as shown in Eq.(11) for Case 1 and Eq.(12) for Case 2, respectively. And we have generated 200 sets of time series data for the two kinds (or cases) of time series, respectively.

$$x_1 = t, x_2 = \sin\left(\frac{1}{8}\pi t\right) \quad (11)$$

$$x_1 = \text{random}, x_2 = \sin\left(\frac{1}{8}\pi t\right) \quad (12)$$

For the two kinds of time series data (400 time series data in total), we have examined the change detection ability and the accuracy of each method (SPRT and NSPR) by setting some various evaluation criteria.

In the experimentation, the prediction model is constructed using the first 40 time points and the rest

of time points from $t=41$ to $t=100$ are used for change detection.

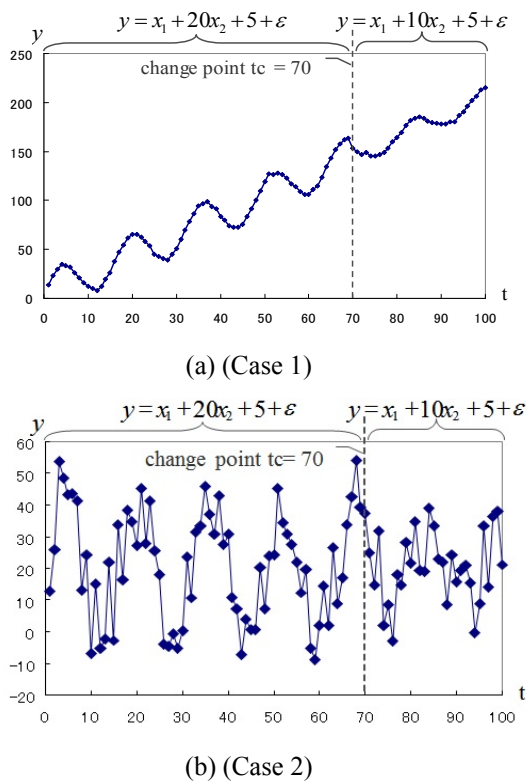


Fig.2. Example of two kinds of time series data generated based on Eq.(10).

(a)Case1 ($x_1=t$, and $x_2 = \sin(\pi/8)$).

(b)Case2 ($x_1=random$, and $x_2 = \sin(\pi/8)$).

We define a two dimensional vector $\mathbf{I}=(I_1, I_2)$ as follows.

$$\mathbf{I} = (I_1, I_2) = \left(\sum_{t=41}^{t=70} f_r(t) \times |t - t_c|, \sum_{t=71}^{t=100} f_r(t) \times |t - t_c| \right) \quad (13)$$

where $t_c=70$, and $f_r(t)$ means the detection frequency at time point t in 200 time series data.

We can consider that the detection ability and the accuracy is high as the absolute value of \mathbf{I} and I_1 approach to 0.

As a result, in the sense of the abovementioned criteria, the NSPR method has shown that it is superior to SPRT for the both kinds of time series data used in the experimentation.

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