

# Plenary Speakers

Plenary Speech Title: will be appeared soon.



**Dr. Jeffrey Johnson** is  
Central Academic Staff  
Professor of Complexity Science and Design  
Faculty of Science, Technology, Engineering &  
Mathematics  
School of Engineering & Innovation

[jeff.johnson](mailto:jeff.johnson)

Publications

## Professional biography

I joined the Design Discipline at the OU in 1981 after three years in the Geography Department at Cambridge University working with Graham Chapman and Peter Gould. Before that I was in the Mathematics Department at Essex University working with Ron Atkin on his theory of Q-analysis for social systems. This has developed into what I now call multilevel [hypernetworks](#). This research involves the application of hypernetwork theory in the design and management of complex social and technical systems at local and global levels in the emerging policy-oriented field of [Global Systems Science](#). The FutureLearn short MOOC [Global Systems Science and Policy: An Introduction](#) starts on 14 March 2016,

My OU undergraduate teaching has included: creating the CADPAC suite of interactive computer exercises for *T363: Computer Aided Design*; creating the SmartLab suite of interactive computer exercises for *T395 - Mechatronics, Designing Intelligent Machine* and co-authoring with Phil Picton the textbook *Mechatronics: Concepts in Artificial Intelligence*; leading the development of *T183 - Design and the Web*, *T184 - Robotics and the meaning of life*, *A178 - Perspectives on Leonardo*, *TM190 - The Story of Maths*, *T218 - Design for Engineers*; and writing the interactive computer exercises for *T174 - Engineering the Future*. I am currently production chair of *T212 Electronics: Sensing, Logic and Actuation* (2017), member of the *T312 Electronics* module production team (2019), and member of the team producing the new *Open STEM Laboratory* giving students remote access to hand-on electronics and robotics experiments.

My OU PhD supervisions include: Richard Murphy - *Constraint-based design synthesis for computer aided design* (1993); Meng Hua - *A neural network based strategy for robot navigation in dynamic environments* (1994), Paul Margerison - *An algorithmic and interactive approach to computer art* (1995), George Glaze - *Graphic design evaluation: towards a rule-based system* (1995), David Durling - *Teaching with style: computer aided instruction, personality and design education* (1996), Claudia Eckert - *Intelligent support*

*for knitwear design (1997), Linda Waddoups - A binary representation for built form (2001), Jack Cawkwell - An automated guided vehicle for local transport (2004), Sunny Bains - Physical computation and embodied artificial intelligence (2004), Nick Scott - Measures from complexity science provide manufacturing companies with insights previously unavailable to them (2004), John Welford - Artificial Intelligent for classifying oral lesions (2005), Pejman Iravani - An architecture for multilevel learning and robotic control based on concept generation (2005), Valery Rose - Evolutionary adaptive self-learning machine vision (2010), Joan Serras - Multidimensional multilevel representation for traffic simulation models (2008), James Law - Abstracting multidimensional concepts for multilevel decisionmaking in multirobot systems (2008), Vikas Chandra - Patenting and publication networks in stem cell research (2009), Paul Morley. Investigation into automated laundry sorting (2012), Anthony Johnston - Sensory augmentation for navigation in difficult urban environments by people with visual impairment (2013), Iain Kusel - A computational model of the emergence of seriation in the young child (2014), Tasos Varoudis - Augmented visibility in architectural space influencing movement patterns (2014), Bjorn Madsen - How to Make the Most Productive Intervention in a Complex Economic System (2015). Current supervision: Cristian Jimenez-Romero - Hypernetworks and spiking neural networks in peer marking for scalable education. Charlotte Foster: Video production in the social welfare charity sector – processes, narrative and ethics (supported by [AHRC Design Star](#))*

My BA and PhD are in mathematics. I am a Fellow of the Institute of Mathematics and its Applications, a Fellow of the British Computer Society, a Chartered Mathematician and Chartered Engineer. I have been director of various engineering and consulting companies and am the CEO of [Vision Scientific Ltd](#), a company I founded with Phil Picton in 1989. I am a Past President of the [Complex Systems Society](#), and a Board Member and Deputy President of the [UNESCO UniTwin Digital Campus for Complex Systems](#). [David Sousa-Rodrigues](#) and I are the OU partners in the European [TOPDRIM](#) Project coordinated by [Emanuela Merelli](#).

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Abstract:



## Plenary Speakers

Plenary Speech Title: **EU-Way Development-Efficient & Rational Development**



[MASATO\\_NAKAGAWA@denso.co.jp](mailto:MASATO_NAKAGAWA@denso.co.jp)

**Mr. Masato Nakagawa, [DENSO CORPORATION](#)**, Executive Fellow (Visiting Professor of [Hiroshima University](#) (Technology transfer theory)) was born at the countryside in Aichi Prefecture in December 30 on 1956, He graduated at [Mechanical Engineering of Faculty of Engineering in Hiroshima University](#) in 1980/03/31 and entered in 1980/04/01 in Denso that belong to Diesel Pump Engineering Department. He lives abroad for a long time such that 5 years at Iowa in USA, one year at London in UK, 10 years at Düsseldorf in Germany, one year and half at Amsterdam in Netherland, one year at Munich in Germany and now Tokyo Office in Japan. He established Powertrain Engineering Center in Germany during his stay in Germany. His hobby is Golf and Creed · Preferred words is



# Plenary Speakers

Plenary Speech Title: **Innovation on Manufacturing Generated by Intelligent Technologies**



**Mr. Ken-ichi Tanaka** is Executive Fellow of Corporate Research & Development Group, Mitsubishi Electric Corporation, Japan

**CV:**

March 1979 Graduated from Aeronautical Engineering, Kyoto University, Japan

March 1981 Completed Master's degree in Aeronautics at Graduate School of Engineering, Kyoto University

**Appointments**

April 1981 Joined Mitsubishi Electric Corporation, Japan

October 2005 Department Manager of Systems Technology Laboratory, Advanced Technology R&D Center, Mitsubishi Electric Corporation, Japan

April 2008 Department Manager of Electromechanical Technology Laboratory, Advanced Technology R&D Center, Mitsubishi Electric Corporation, Japan

April 2010 General Manager of Advanced Technology R&D Center, Mitsubishi Electric Corporation, Japan

April 2014 Executive Fellow of Corporate Research & Development Group, Mitsubishi Electric Corporation (current position), Japan

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Abstract:

## Invited Speakers

Invited Speech Title will be appeared soon.



**Dr. Henrik Hautop Lund** is [Professor at Technical University of Denmark](#), is [head of the Center for Playware](#), and has published more than 175 scientific papers and several patents. He has served in [the Danish National Research Council](#). He is World Champion in RoboCup Humanoids Freestyle 2002, has developed shape-shifting modular robots, and has collaborated closely on robotics, ALife and AI with

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companies like LEGO, Kompan, BandaiNamco, etc. for the past two decades. His Center for Playware at the Technical University of Denmark has a long track record of developing modular robotic playware for playful contextualized IT training in Sub-Saharan Africa, for playful rehabilitation for sport, for music, for wearable, for play, and for education. These modular playware technology developments include I-Blocks (LEGO bricks with processing power) and modular interactive tiles (larger bricks for physical rehab). Further, with the development of East-Africa's first science and business park, local entrepreneurship has been fostered amongst students graduating from the university degree programs in contextualized IT. Combining such skills, it became possible to develop technical skill enhancing football games and global connectivity based on modular playware for townships in South Africa for the FIFA World Cup 2010. Lately, together with international pop star and World music promoter Peter Gabriel, he has developed the MusicTiles app as a music 2.0 experience to enhance music creativity amongst everybody, even people with no initial musical skills whatsoever, and made physical modules for Peter Gabriel's live stage performance. In all cases, professor Henrik Hautop Lund and his research center develop modular playware technology in a playful way to enhance learning and creativity amongst anybody, anywhere, anytime.

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Abstract:

## Invited Speakers

Invited Speech Title will be appeared soon.



[Luigipagliarini@gmail.com](mailto:Luigipagliarini@gmail.com)

**Dr. Luigi Pagliarini** is Professor of [The Academy of Fine Arts of Macerata](#), Italy, an artist, psychologist, multimedia and software designer, expert in robotics, AI and Artificial Life. He is currently [Professor at the Academy of Fine Arts of Macerata](#) (Italy) and Consultant Professor at DTU Center for Playware (Denmark). He has published in different international books, journals, congresses and conferences proceedings and has been rewarded with international prizes more than once. He has exhibited his work in different museums and institutions all over the world. Luigi Pagliarini has also worked for many different institutes and universities as professor or researcher and, as consultant, with many enterprises and multinational factories. His work has often been reported on many international newspapers, magazines and televisions.

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Abstract:

## Invited Speakers

Invited speech title: **Natural Computing Paradigm – A Concise Introduction**



**Dr. Takashi Yokomori** is a Professor of Mathematics Department, Faculty of Education and Integrated Arts and Sciences, Waseda University, Tokyo.

**Research themes:** Automata and Formal Language Theory, Computational Learning Theory (e.g., Grammatical Inference), Theory of Natural Computing (e.g., Molecular Computing Theory, Bio-informatics, Chemical Reaction Computing)

[yokomori@waseda.jp](mailto:yokomori@waseda.jp)

### **Educational and Professional Careers:**

- 1998 -- (present) : Professor, Waseda University, Japan
- 1997 -- 98: Professor, University of Electro-Communications, Japan
- 1989 -- 97: Associate Professor, University of Electro-Communications, Japan
- 1983 -- 89: Researcher, IIAS-SIS, Fujitsu Limited, Japan
- 1982 -- 83: Postdoctoral Fellow at Pennsylvania University, USA
- 1981 -- 82: Postdoctoral Fellow at McMaster University, Canada
- 1979 -- 81: Research Associate, Sanno College, Japan
- 1979 : D.Sci., University of Tokyo, Japan
- 1976 : M.Sci., University of Tokyo, Japan
- 1974 : B.Sci., University of Tokyo, Japan

### **Academic Activities:**

Please refer to: <http://www.edu.waseda.ac.jp/~yokomori/activitye.html>

### **Selected Publications: (since 2010)**

- F. Okubo and T. Yokomori : The computational power of capability of chemical reaction automata, *Natural computing*, Vol.15, pp.215-224, 2016.
- F. Okubo and T. Yokomori : Finite Automata with Multiset Memory: A New Characterization of Chomsky Hierarchy, *Fundamenta Informaticae*, Vol.138, pp.31-44, 2015.
- F. Okubo and T. Yokomori: Recent developments on reaction automata theory: A survey, in "Recent Advances in Natural Computing" (Selected results from the IWNC 7 Symposium), Series: Mathematics for Industry, vol.9 (Y. Suzuki and M. Hagiya, eds.), pp.1-22, Springer, 2014.
- G. Rozenberg et al.(Eds.): Handbook of Natural Computing, Chapter 34:"Molecular Computing Machines--Computing Models and Wet Implementations (by M. Hagiya, S. Kobayashi, K. Komiya, F. Tanaka, T. Yokomori), Springer, 2012.
- F. Okubo, S. Kobayashi and T. Yokomori : On the properties of language classes defined by bounded reaction automata, *Theoretical Computer Science*, Vol.454, pp.206-221, 2012.
- F. Okubo, S. Kobayashi and T. Yokomori : Reaction Automata, *Theoretical Computer*

*Science*, Vol.429, pp.247-257, 2012.

- F. Okubo and T. Yokomori : On the Hairpin Incompletion, *Fundamenta Informaticae*, Vol.110, pp.255-269, 2011.

- M. Ionescu, G. Paun, M. Perez-Jimenez and T. Yokomori : Spiking Neural dP-systems, *Fundamenta Informaticae*, Vol.111, pp.423-436, 2011.

- F. Okubo and T. Yokomori : Morphic Characterizations of Language Families in Terms of Insertion Systems and Star Languages, *Intern. J. of Foundations of Computer Science*, Vol.22, No.1, pp.247-260, 2011.

- F. Manea, V. Mitran and T. Yokomori : Some Remarks on the Hairpin Completion, *Intern. J. of Foundations of Computer Science*, Vol.21, No.5, pp.859-872, 2010.

- O. Ibarra, M. Perez-Jimenez and T. Yokomori : On Spiking Neural P-systems, *Natural Computing*, Vol.9, pp.475-491, 2010.

(For full details, please refer to:

<http://www.edu.waseda.ac.jp/~yokomori/publiste.html> )

**[Contact]**

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Abstract: Natural computing (NC) is an emerging research area that investigates computing techniques and models inspired by nature, and it also investigates phenomena taking place in nature in terms of computational methodologies. Thus, NC research congenitally bridges between computer science and a broad spectrum of fundamental research fields including biology, chemistry, physics, medical science, and so forth.

In this talk, we give a concise introduction to this new paradigm of NC. Specifically, we give an overview of selected topics of the fields in which the stress is primarily put on theoretical achievements in computing paradigms such as molecular computing and chemical computing.



## Invited Speakers

Invited Speech Title: **Artificial Immune Ecosystems: challenges for a new generation of bio-inspired secure and resilient systems**



**Dr. Pierre Parrend** is the head of the Computer Science and Mathematics department at ECAM Strasbourg-Europe engineer school. He is a member of the research team 'Complex Systems and Translational Biology' at ICube Laboratory of the University of Strasbourg, and the head of the e-laboratory '4PFactory : the factory of the future' of the UNESCO Unitwin Complex System-Digital Campus. His research interests encompass artificial

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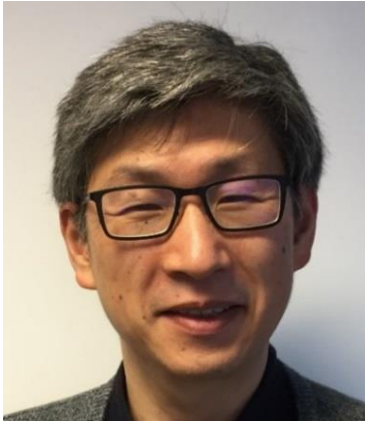
immune ecosystems, evolutionary strategies for optimisation and anomaly detection, as well as emergent properties of human organisations.

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Abstract: The rapid evolution of IT ecosystems significantly challenges the security models our infrastructures rely on. Beyond the old dichotomy between open and closed systems, it is now necessary to securely handle the interaction between heterogeneous devices building dynamic ecosystems. To this regard, bio-inspired approaches provide a rich set of conceptual tools, but have failed to lay the basis for robust and efficient solutions. Our research effort intends to revisit the contribution of artificial immune system research to bring immune properties: security, resilience, distribution, memory, into IT infrastructures. We introduce the concept of artificial immune ecosystems, which encompass a comprehensive immune protocol, libraries for detection and investigation of anomalies, and an underlying middleware layer, for bringing immunity to IT infrastructures, the Cloud, and IoT environment.

## Invited Speakers

Invited Speech Title : **Harnessing over a Million CPU Cores to Solve a Single Hard Mixed Integer Programming Problem on a Supercomputer**



**Dr. Yuji Shinano** is Researcher, [Zuse Institute Berlin](#), Germany

**CV:**

1997 PhD Engineering, Tokyo University of Science, Japan

1994 MS Engineering, Tokyo University of Science, Japan

1992 BS Engineering, Tokyo University of Science, Japan

[shinano@zib.de](mailto:shinano@zib.de)

### Appointments

2010/04 – present Researcher, Zuse Institute Berlin, Germany

2010/10– present Guest Associate Professor, The Institute of Statistical Mathematics, Japan

2009/03 – 2009/12 Visiting Zuse Institute Berlin for Sabbatical leave

2004 – 2010/03 Associate Professor, Tokyo University of Agriculture and Technology, Japan

1999 – 2004 Assistant Professor, Tokyo University of Agriculture and Technology, Japan

1997 – 1999 Research Assistant, Tokyo University of Science, Japan

1994 – 1997 Research Fellow of the Japan Society for the Promotion of Science, Japan

### Recent Publications

1. Y. Shinano, T. Achterberg, T. Berthold, S. Heinz, T. Koch. ParaSCIP: a parallel extension of SCIP. *Competence in High Performance Computing 2010*, Christian Bischof, Heinz-Gerd Hegering, Wolfgang Nagel, Gabriel Wittum (Eds.), pp. 135–148, 2012.
2. T. Koch, T. Ralphs, Y. Shinano. Could we use a million cores to solve an integer program? *Mathematical Methods of Operations Research*, 76(1):67–93, 2012.
3. Y. Shinano, T. Achterberg, T. Berthold, S. Heinz, T. Koch, M. Winkler. Solving hard MIPLIB2003 problems with ParaSCIP on supercomputers: An update. in *Proceedings of the 2014 IEEE International Parallel & Distributed Processing Symposium Workshops, IPDPSW'14*, (Washington, DC, USA), pp. 1552–1561, IEEE Computer Society, 2014.
4. G. Gamrath, T. Koch, S. J. Maher, D. Rehfeldt, Y. Shinano. SCIP-Jack - A solver for STP and variants with parallelization extensions. *Math. Prog. Comp.* pp.1 – 66, 2016.

5. Y. Shinano, T. Achterberg, T. Berthold, S. Heinz, T. Koch, M. Winkler: Solving open MIP instances with ParaSCIP on supercomputers using up to 80,000 cores. In: 2016 IEEE International Parallel and Distributed Processing Symposium (IPDPS), pp. 770–779. IEEE Computer Society, Los Alamitos, CA, USA, 2016.
6. Y. Shinano, S. Heinz, S. Vigerske, M. Winkler. FiberSCIP - A shared memory parallelization of SCIP. accepted for publication in INFORMS Journal on Computing, 2017.

### **Research Interests and Expertise**

My research expertise is in the field of mathematical optimization programming problems and parallel computing. I am interested in the application of parallel computing to solve very hard discrete optimization problem instances in the real-world.

Currently I am involved in the development of the SCIP Optimization Suite at the Zuse Institute Berlin. I am the developer of UG which is a software framework to parallelize state-of-the-art MIP solvers and is a package in the SCIP Optimization suite.

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### **Abstract:**

Mixed integer programming (MIP) is a general form to model combinatorial optimization problems and has many industrial applications. The performance of MIP solvers, software packages to solve MIPs, has improved tremendously in the last two decades and these solvers have been used to solve many real-world problems. However, against the backdrop of modern computer technology, parallelization is of pivotal importance. In this way, ParaSCIP is the most successful parallel MIP solver in terms of solving previously unsolvable instances from the well-known benchmark instance set MIPLIB by using supercomputers. It solved two instances from MIPLIB2003 and 12 from MIPLIB2010 for the first time to optimality by using up to 80,000 cores of supercomputers. Additionally, a specialized version of ParaSCIP for solving Steiner tree problems called SCIP-Jack solved three open instances from the Steiner tree test benchmark set PUC. ParaSCIP has been developed by using the Ubiquity Generator (UG) framework, which is a general software package to parallelize any state-of-the-art branch-and-bound based solvers. The UG framework is currently being used to develop ParaXpress, a distributed memory parallelization of the commercial MIP solver Xpress. Moreover, it is being used to parallelize PIPS-SBB, a solver for stochastic MIPs. Since Xpress is a multi-threaded solver and ParaSCIP can run at least 80,000 processes in parallel for solving a single MIP, ParaXpress could handle over a million CPU cores. Furthermore, the parallelization of PIPS-SBB by the UG framework has the potential to also handle over a million CPU cores. In this talk, a ground design of the UG framework and its latest extensions to harness over a million CPU cores will be presented and preliminary computational results will be provided.

## Invited Speakers

### Invited Speech Title: **Predicting Trust of Humanoid Robots in Service Scenarios; Implications for Human-Robot-Human Interaction**



**Dr. Halimahtun M. Khalid** is President of Damai Sciences, Malaysia. She obtained her PhD in cognitive ergonomics from University College London, UK. She has 35 years of knowledge and experience in HCI, human factors and ergonomics. She was Professor of Cognitive Ergonomics at Universiti Malaysia Sarawak, Malaysia, where she established the Institute of Design & Ergonomics Application, the Centre for Applied Learning & Multimedia, and the first Virtual Reality Centre. She has delivered several keynotes at international conferences, and has more than 100 publications in refereed journals and proceedings. She received research grants from the

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European Commission and US Air Force for projects related to mass customization, cultural cognition, disaster attitudes, and human-robotic trust. Dr. Khalid is the Founder and Past President of the Human Factors and Ergonomics Society Malaysia, and Past President of the Southeast Asian Network of Ergonomics Societies. She is Past Chair of the Science Technology & Practice Committee of the International Ergonomics Association (IEA), and Past Chair of the Affective Design Technical Committee of the IEA. She is a Certified Human Factors Professional with BCPE USA, and a Fellow of the International Ergonomics Association.

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#### Abstract:

Trust is a key element in the development of effective human-robot-human relationships. In particular, trust affects system effectiveness as it relates to safety, performance, and usability. With the development and integration of humanoid robots in human teams, the issue of predicting trust has become a focal concern. Setting the scene, we will trace a decade of research into human-robotic trust starting from 2006. One of the research gaps is the lack of a reliable measure of human-robotic trust. Past studies have emphasized on subjective measurements only. In this plenary, we will present a method where subjective (general trust, psychological) and objective (physiological) measures were mapped to predict human trust of humanoid robots in performing social tasks in a multi-actor, multi-dialog, and bilingual contexts. We will present the findings from two studies, involving different humanoid robots and diverse types of interactive dialogs in business, disaster and healthcare application domains. Extraction of objective measures includes facial expressions, voiced speech, camera-based heart rate, and gestural posture. Subjective trust comprised fifteen items that measured ability, benevolence and integrity. A neuro-fuzzy algorithm extracted rules

that predicted low, medium and high trust levels. The implications of the findings on future human-robotic trust relationships and limitations of the method will be discussed.