ICAROB2019 DOIs List

Description	ICA	KOR5019 DOIS	LISt	
Management Man	ID	DOI	URL	Title
Column	GS1-1	10.5954/ICAROB.2019.GS1-1	https://www.doi.org/10.5954/ICAROB.2019.GS1-1	
Description	GS1-2 GS1-3			
Political Control Company Company Company Company Control Cont	GS2-1	•		Automated Guided Vehicle System Analysis in Foam Manufacturing Plant Using Petri-
1998 Text	GS2-2	10.5954/ICAROB.2019.GS2-2	https://www.doi.org/10.5954/ICAROB.2019.GS2-2	Preliminary Comparative Experiments of Support Vector Machine and Neural Network
Septiment Sept	GS2-3	10.5954/ICAROB.2019.GS2-3	https://www.doi.org/10.5954/ICAROB.2019.GS2-3	Position Tracking Error Constrained Super-Twisting Dynamic Surface Control with
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Tables Testing Test	GS4-1			The Relevance Research among Destination Image, Brand Trust and Satisfaction:
0.9594/0.4808.2019.0554-1 0.9594/0.4808.2019.0554-1 0.9594/0.4808.2019.0554-1 0.9594/0.4808.2019.0554-1 0.9594/0.4808.2019.0554-1 0.9594/0.4808.2019.0554-2	GS4-2			
10.5554/CARGO.2019.055-1	GS4-3			
International Control Pattern of Central Pattern Generate Output Waveform International Control Pattern International Co	GS4-5	10.5954/ICAROB.2019.GS4-5	https://www.doi.org/10.5954/ICAROB.2019.GS4-5	Example
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10.9991/CAROR 2019 CS-1 10.9991/CAROR 2019 CS-5 10.9991/CAROR 20	GS5-2	10.5954/ICAROB.2019.GS5-2	https://www.doi.org/10.5954/ICAROB.2019.GS5-2	
13.9354/CAROB 2019 GSS-5 13.9954/CAROB 2019 GSS-5 13.9954/CAROB 2019 GSS-7 13.9954/CAROB 2019	GS5-3	10.5954/ICAROB.2019.GS5-3	https://www.doi.org/10.5954/ICAROB.2019.GS5-3	
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1.5954/CAR08.2019.51-1 1.5954/CAR08.2019.5				
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15.9547/CAROB 2019.051-12 15.9547/CAROB 2019.051-12 15.9547/CAROB 2019.051-13 15.9547/CAROB 2019.051-14 15.9547/CAROB 2019.051-15 15.9547/CAROB 2019.051-15 15.9547/CAROB 2019.051-16	IS-2			
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OS13-1	10.5954/ICAROB.2019.OS13-1	https://www.doi.org/10.5954/ICAROB.2019.OS13-1	Research on a Non-Invasive Measuring Method of Blood Glucose Concentration Based
OS13-10	10.5954/ICAROB.2019.OS13-10	https://www.doi.org/10.5954/ICAROB.2019.OS13-10	on Electrical Impedance Spectrum Research On Embedded Electrical Impedance Measurement System
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OS14-3	10.5954/ICAROB.2019.OS14-3	https://www.doi.org/10.5954/ICAROB.2019.OS14-3	Time-Varying Lyapunov Function for Mechanical Systems
OS14-4	10.5954/ICAROB.2019.OS14-4	https://www.doi.org/10.5954/ICAROB.2019.OS14-4	Optimizing Control Parameters of Space Robot Manipulator for Pulsar X-ray Interference Measurement
OS15-1	10.5954/ICAROB.2019.OS15-1	https://www.doi.org/10.5954/ICAROB.2019.0S15-1	Pulse Pose Follow Control and Simulation for a 4-DOF Pulse Diagnosis Robot
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OS15-3	10.5954/ICAROB.2019.OS15-3	https://www.doi.org/10.5954/ICAROB.2019.OS15-3	Agent Systems under Stochastic Communication Noises
OS15-4	10.5954/ICAROB.2019.OS15-4	https://www.doi.org/10.5954/ICAROB.2019.0S15-4	Distributed Energy Resource Control Based on Multi-Agent Group Consensus
			Robust Adaptive Control of Air-to-air Refueling Boom with State-dependent Output
OS15-5	10.5954/ICAROB.2019.OS15-5	https://www.doi.org/10.5954/ICAROB.2019.OS15-5	Constraints
OS16-1	10.5954/ICAROB.2019.OS16-1	https://www.doi.org/10.5954/ICAROB.2019.OS16-1	Skill Model Estimation of Ability for Reading Drawings
OS16-2	10.5954/ICAROB.2019.OS16-2	https://www.doi.org/10.5954/ICAROB.2019.OS16-2	Learning Simulation based on a Computational Model of Neuromodulators
OS16-3	10.5954/ICAROB.2019.OS16-3	https://www.doi.org/10.5954/ICAROB.2019.OS16-3	Estimation of Programming Learning Achievement by Line Tracing Robot
OS16-4	10.5954/ICAROB.2019.OS16-4	https://www.doi.org/10.5954/ICAROB.2019.OS16-4	Development of Cultivate Computational Thinking using Finger Robot
OS17-1	10.5954/ICAROB.2019.OS17-1	https://www.doi.org/10.5954/ICAROB.2019.OS17-1	Different Type of Interaction or Decision Error Contribute to Functional Differences
OS17-2	10.5954/ICAROB.2019.OS17-2	https://www.doi.org/10.5954/ICAROB.2019.OS17-2	Evaluation for the Synchronization of the Parade with OpenPose
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