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| The 2016 International Conference onArtificial Life and Robotics (ICAROB 2016)21st AROB Anniversary  |

* **November 25, 2015 Abstract submission due date**
* **November 25, 2015 OS, GS, PS, TS proposal submission due date**
* **October 31, 2015 Final early bird registration due date**
* **November 30, 2015 Notification of acceptance due date**
* **December 20, 2015 Final paper submission due date**

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| **OS: Organized Session GS: General Session PS: Poster Session TS: Tutorial Session** |

**Publication**

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**3rd Call for Papers**

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**Important Dates**

**The 2016 International Conference on Artificial Life and Robotics (ICAROB 2016)** will be held atHorutoHall, OITA, JAPAN, from January 29 to 31, 2016. This Conference will provide new development of modern technologies concerning *Robotics, Networking and Artificial Life* associated with computer simulations, hardware designs, and networking of state-of-the-art technologies to researchers, and to share findings on how advancements in robotics, networking, complexity and artificial life technologies that relate to inter-disciplinary approach to the field such as artificial intelligence, virtual reality, and computer science are creating the basis for exciting new research and applications in various fields listed in the following topics. **Please submit papers to ICAROB 2016 Web Site from** [**http://alife-robotics.co.jp/**](http://alife-robotics.co.jp/)**.**

**January 29-January 31, 2016**

**Okinawa Convention Center, Ginowan, JAPAN**

The 2016 International Conference on Artificial Life and Robotics ((ICAROB)



Usa Shrine (Before BC era three goddesses “Shikitusima-himemikoto, Hasizu-himemikoto, Tag

iri-himemikoto descended on the earth of Usa from heaven.) The shrine is called Total Motomiya

Hachiman Shrine Usa located in Oita Prefecture.

* Analysis of randomized algorithms
* Artificial nervous systems for robots
* Artificial living
* Bipedal robot
* Cognitive science
* Evolutionary computations
* Intelligent control
* Medical surgical robot
* Computational Molecular biology
* Nano-robotics
* Neuroscience
* Neuro-computer
* Neuromorphic systems
* Reinforcement learning system & genetic programing
* Software development support method
* [System cybernetics](http://www.hiroshima-u.ac.jp/en/cyb/)
* Foundation of computation and its application
* Unmanned aerial systems technologies
* Unmanned aerial systems designing, controls and navigation
* Artificial sciences
* Artificial mind research
* Brain science and computing
* Artificial intelligence & complexity
* adaptive behavior and metabolism
* Data mining
* Fuzzy control
* Human-welfare robotics
* Micro-machines
* Multi-agent systems
* Networking
* Pattern recognition
* Virtual reality
* Environment navigation and localization
* Facial expression analysis, music recommendation and augmented reality
* Applications in Kansei engineering
* Unmanned aero vehicles
* Intelligence in biological systems
* Agent-based software
* Chaos
* Computer graphics
* DNA computing
* Genetic algorithms
* Image processing
* Management of technology
* Insect-like aero vehicles
* Nano-biology
* Neural circuits
* Unmanned underwater vehicles
* Quantum computing
* Robotics
* Visualization
* Disasters robotics
* Empirical research on network and MOT
* (Others etc.)

**Topics of interest include, but are not limited to**

**Accepted papers will be published in the Proceedings of the ICAROB. Extended versions of the selected papers will be published In the journal：Robotics, Networking and Artificial Life (will be indexed by SCI, EI and SCOPUS) (** [**http://www.atlantis-press.com/publications/jrnal/**](http://www.atlantis-press.com/publications/jrnal/) **) published by Atlantis Press.**

**Registration Fee**

**Registration fee \55,000 (\50,000 for early birds) and \30,000 for Students (\25,000 for early birds) not including Banquet Fee**

**Organized by**

International Steering Committee of International Conference on Artificial Life and Robotics (ICAROB)

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IEEE Robotics and Automation Society (USA)

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